



UNIVERSITY OF MASSACHUSETTS  
DARTMOUTH

ECE544: Fault-Tolerant Computing &  
Reliability Engineering

## Midterm Exam Review

Instructor: Dr. Liudong Xing

Fall 2022

## Administrative Issues (10/12, Wednesday)

- Homework#4 due **Today**
- Midterm Exam
  - On **Oct. 17, Monday**
  - Review session **Today**
- Project Meeting
  - Due **Oct. 28, Friday**

## Midterm Exam

- **Time & Place:**
  - 3:30pm-4:55pm on October 17 (Monday)
  - SENG212
- **Form:**
  - Open book and open notes
  - Individual work
- **Preparation**
  - Lecture notes # 1 – 9
  - Homework #1 - #4
  - Relevant readings

## Midterm Exam Review

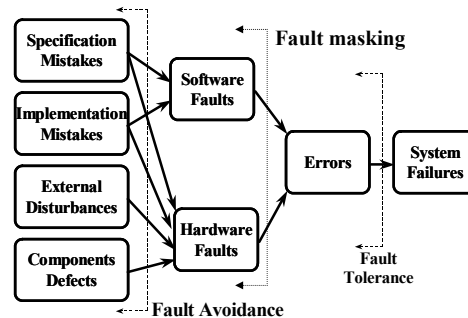
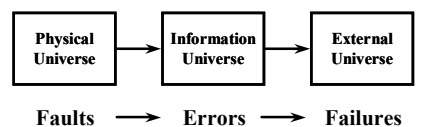
- I. Fundamental Concepts
- II. Fault Tolerance Techniques
- III. Reliability Modeling and Analysis Techniques

## Part I: FTC & RE Overview

- **Basic concepts:** Fault-tolerant systems, fault-tolerance, fault-tolerant computing, fault avoidance; reliability, availability, safety, testability, maintainability, performability, graceful degradation, dependability
- **Applications:** Long-life; Critical computation; High availability applications
- **General motivation (4 examples)**
  - **Why fault tolerance?** To increase length of time a system will operate correctly; to minimize amount of time a system is down; to ensure safe operation; to meet certain design requirements
  - **Why reliability analysis?** To predict the reliability of a system for a specified period of time; compare alternative architecture design solution; facilitate trade-off studies for various FT techniques

## Part I: Faults, Errors, and Failures

- Concepts
  - **Fault:** a physical defect, imperfection, or flaw that occurs in HW or SW comp.
  - **Error:** the occurrence of an incorrect value in some unit of information; the manifestation of a fault; a deviation from accuracy or correctness
  - **Failure:** a deviation from the expected performance of a system
- Three universe model and cause-and-effect relationship



## Midterm Exam Review

- I. Fundamental Concepts
- II. Fault Tolerance Techniques**
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### Part II: Fault Tolerance Techniques

Hardware redundancy	Information redundancy	Time redundancy	Software redundancy
-- Passive	-- Parity	-- Transient	-- Consistency check
-- Active	-- m-of-n	-- Permanent	-- Capability check
-- Hybrid	-- Berger	*Alter. Logic	-- RB
	-- Checksum	*RESO	-- NVP
	-- Cyclic	*RESWO	-- NSCP
	-- Arithmetic		

## Hardware Redundancy Techniques (1)

- **Passive** redundancy uses fault masking to hide the occurrence of faults and prevent the faults from resulting in errors and failures
  - **TMR** is the most common form, (multi-stage) triplicated TMR can overcome the effects of the single-point of failure (voter)
  - **Hardware and software voting** have their pros and cons, the decision must be made based on several factors
  - **Mid-value select** and **Voting on part of data** techniques can be used to alleviate the problem of disagreeing results in a NMR system

## Hardware Redundancy Techniques (2)

- **Active** redundancy uses detection, location, and recovery techniques (reconfiguration)
  - **Duplication with comparison** can only detect faults, not tolerate them
  - **Hot standby sparing** can minimize the disruption in performance but consume more power than **cold standby sparing**
  - **Warm standby sparing is a tradeoff between hot and cold**

## Hardware Redundancy Techniques (3)

- **Hybrid** redundancy employs both fault masking and reconfiguration
  - Requires enough hardware to use voting & for spares
  - The most expensive in terms of hardware required to implement a system, used when highest levels of reliability are desired
  - **NMR with spare technique** can accomplish the same results using fewer hardware modules than passive approaches, but with fault detection/location/recovery schemes
  - **Self-purging redundancy** technique uses the system output to remove modules whose output disagrees with the system output

## Information Redundancy Techniques (1)

- **Basic concepts**
  - Code, code word, binary code, error detecting/correcting code, encoding /decoding process
  - Bit, symmetric, asymmetric, unidirectional, and byte errors
  - Hamming distance, code distance, error detection/correction capabilities (3 theorems)

## Information Redundancy Techniques (2)

- Parity codes
  - **Single-bit parity codes**: Detects all errors which involve an odd number of bits
  - **Multiple-bit parity codes**: Hamming SEC codes
    - Calculate number of check bits  $K$
    - Arrange bit positions
    - Generate the check bits
    - Correct the erroneous bit according to the syndrome word
  - **Horizontal and vertical parity codes**: can correct (detect&locate) any single-bit errors in groups of data words

## Information Redundancy Techniques (3)

- **m-of-n codes** (separable/non-separable) can detect all single-bit errors and all multiple, unidirectional errors
- **Berger codes** are separable unidirectional error detecting codes; which can be manipulated so that they are invariant to the arithmetic/logical operations
- **Checksum** (SPC/DPC/Honeywell/Residue) codes are separable codes and can only detect errors but not locate/correct errors

## Information Redundancy Techniques (4)

- **Cyclic codes (separable/non-separable)**
  - Cyclic codes are invariant to the end-around shift operation; are best represented and analyzed using polynomial algebra
  - Cyclic coding can be implemented using combinatorial circuit composed of exclusive-OR gates
- **Arithmetic codes**
  - AN codes are invariant to addition & subtraction, but not multip. & division
  - Both residue and inverse-residue codes are separable codes

## Information Redundancy Techniques (5)

- To select a proper coding scheme in designing the system, three major decisions must be made
  - Whether or not the code needs to be separable
  - Whether error detection, error correction, or both are required
  - Number of bit errors needs to be detected or corrected



## Time Redundancy Techniques

- Time redundancy can reduce the amount of extra hardware at the cost of using additional time in achieving fault detection/correction
- Often employed to distinguish between **permanent** and **transient** faults
- Time redundancy **combined with coding schemes** can detect permanent faults (different encoding functions)
  - Alternating logic
  - Recomputing with shifted operands
  - Recomputing with swapped operands
- Time redundancy can provide **error correction** if computation is repeated 3 or more times!

## Software Redundancy Techniques

- The addition of redundant software to a system, for the purpose of achieving fault tolerance
  - **Extra code lines or routines**
    - Consistency checks: Use a priori knowledge about the characteristics of information to verify the correctness of the information
    - Capability checks: Performed to verify if a system possesses the capability expected
  - **Extra versions of the complete program**
    - Recovery blocks (RB)
    - N-version programming (NVP)
    - N-self-checking programming (NSCP)

## Midterm Exam Review

- I. Fundamental Concepts
- II. Fault Tolerance Techniques
- III. Reliability Modeling and Analysis Techniques
  - Reliability measures
  - Fault trees and cutsets-based analysis

## Quantitative Evaluation Measures

- Time to failure ( $T$ ): a r.v. describing the time elapsing from when a component is put into operation until it fails for the first time
  - $F(t)$ : cumulative distribution function (c.d.f) of the r.v.  $T$ ;  
**failure function**
  - $f(t)$ : probability density function (p.d.f.) of  $T$
- Reliability/survivor function  $R(t)=1-F(t)$
- Failure rate (hazard rate/function)  $z(t)$ 
  - The bathtub curve: burn-in/infant mortality period, **useful-life period**, wear-out period

## Quantitative Evaluation Measures

- Mean time to failure (MTTF)
  - Mean time to repair (MTTR), Mean time between failure (MTBF)
  - $MTBF = MTTF + MTTR$

- Mean residual life (MRL) at age  $t$ :

$$MRL(t) = \int_0^{\infty} R(x|t) dx = \frac{1}{R(t)} \int_t^{\infty} R(x) dx$$

- Relationship between  $F(t)$ ,  $f(t)$ ,  $z(t)$ ,  $R(t)$ , and MTTF
- Time to failure distributions: **exponential distributions** with constant failure rate and memory-less property

## Reliability Modeling and Analysis (System-Level)

- Fault tree
- Minimal cut-set
  - Inclusion-exclusion (I/E)
  - Sum of disjoint products (SDP)

*.....More after Midterm Exam*

## Fault Trees

- A **failure-oriented** model, expressing combinations of component failures that can lead to system failure
- **Top-down construction**: consists of a top event (system failure), basic events (component failures), and gates that connect the events.
- **Fault trees** consist of only static gates (AND, OR, K/N) and model static systems whose failures are simply logical combinations of component failures
- Analysis of fault trees is based on **minimal cutsets**

## Minimal Cutsets and Analysis

- **Cut-sets**: a set of components which by failing causes the system to fail; a cut set is **minimal** if it cannot be reduced without losing its status as a cut set
- **Unreliability** analysis of fault trees using **minimal cutsets**

Inclusion/Exclusion (IE)	Sum of Disjoint Products(SDP)
$Pr\left\{\bigcup_{i=1}^n C_i\right\} = \sum_{i=1}^n Pr\{C_i\}$ $- \sum_{i < j} Pr\{C_i \cap C_j\}$ $+ \sum_{i < j < k} Pr\{C_i \cap C_j \cap C_k\}$ $\mp \dots$ $\pm Pr\left\{\bigcap_{i=1}^n C_i\right\}$	$Unreliability = Pr\left\{\bigcup_{i=1}^n C_i\right\}$ $= P(C_1) + P(\overline{C_1}C_2) + P(\overline{C_1}\overline{C_2}C_3)$ $+ \dots + P(\overline{C_1}\overline{C_2}\overline{C_3}\dots\overline{C_{n-1}}C_n)$

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*Good  
Luck!!!*