

ECE 454/544: Fault-Tolerant Computing & Reliability Engineering



Lecture #17 – Network Reliability

Instructor: Dr. Liudong Xing
Fall 2022

Administrative Issues (Nov. 21, Monday)

- Homework#7 (last one☺)
 - Due Today
- Project final report
 - Due by Nov. 30, Wednesday
 - Please check out the Report Guidelines for requirements
- Project presentation slides
 - Due by Dec. 5, Monday
 - Please check out the Presentation Guidelines for requirements

Topics

- Graph models and definitions
- Evaluation approaches

Network Graph Model

- A **probabilistic** graph $G=(V, E)$
 - V: a set of nodes/vertices (network elements, such as terminals and routers)
 - E: a set of links (communication paths)
 - with failure probabilities assigned to each node and/or link in the graph.

Definitions of Network Reliability

- In general, the probability that the system operates successfully for a given period time under environmental conditions (temperature, atmosphere, weather, system load and traffic)
- Reliability of a network G
 - probability that G supports a given operation

Definition (Cont'd)

- Three kinds of network reliability
 - **Two-terminal reliability** (terminal-pair): two given vertices can communicate
 - **All-terminal reliability**: operation requires each pair of vertices is able to communicate via at least one operational path
 - **K-terminal reliability**: operation requires a few vertices, a subset K of V , to communicate each other

Example Evaluation Methods (Two-Terminal Reliability)

- State space enumeration method
- Cut-set and tie-set method
- Graph transformation method
- Binary decision diagrams-based method

Reference:

1. Xinyu Zang, Hairong Sun, Kishor S. Trivedi, "A BDD-Based Algorithm for Reliability Graph Analysis",
<http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.44.6169>
2. Corinne Lucet, Jean-Francois Manouvrier, "Exact Methods to compute Network Reliability",
<http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.27.7190>
3. Martin L. Shooman, "Reliability of Computer Systems and Networks: Fault Tolerance, Analysis, and Design", John & Sons Wiley, 2002, ISBN 0-471-29342-3 (Chapter 6).

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State-Space Enumeration

- Enumerate all possible combinations where each of the edges in E can be good or bad $\rightarrow 2^{|E|}$ disjoint combinations
- Each combination \rightarrow an event
- Network reliability is the probability of the union of the subset of the events that contain a path between s and t .

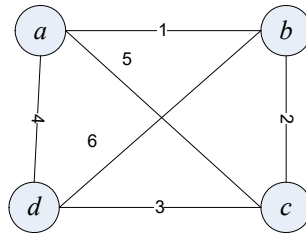
$$R_{NW} = P(E_1 \cup E_2 \cup \dots) = P(E_1) + P(E_2) + \dots$$

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Hands-On Problem (1)

- Assume all nodes are perfect, each link has a failure probability of $q=0.1$. Find the two-terminal reliability from a to b ?



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State-Space Enumeration (Cont'd)

- Procedure is clear
- Time-consuming
- Exponential event space

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Cut-set and Tie-set Method

- A **tie/path set**
 - a group of edges which forms a connection between input and output when traversed in the arrow direction
- A **cut set**
 - A set of edges which interrupts all connections between input and output when removed from the graph
- **Minimal**
 - No node or edge is traversed more than once
 - A minimal tie (cut) set has no subset of edges that are a tie (cut) set.

Cut-set and Tie-set Method (Cont'd)

- There are i tie sets between s and t

$$R_{NW} = P(T_1 \cup T_2 \cup \dots \cup T_i)$$

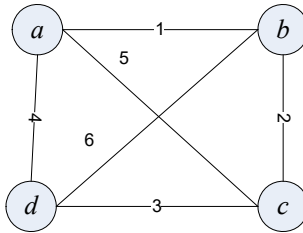
- There are j cut sets between s and t

$$R_{NW} = 1 - P(C_1 \cup C_2 \cup \dots \cup C_j)$$

- Solved using I/E or SDP method

Hands on Problem (2)

- Final the minimal tie sets and cut sets
- Find the two-terminal reliability from a to b , given that each edge has a failure probability $q=0.1$.



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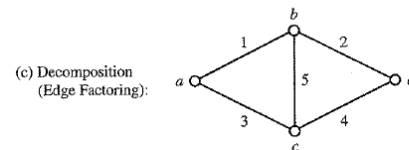
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Transformation Method

- Transform a network into a simpler network (or set of networks) by successively applying transformation
- Three basic transformations

(a) Series: = $P_{ac} = P(1 \cdot 2)$

(b) Parallel: = $P_{ab} = P(1 + 2)$



Expand about 5: $R_{ad} = [P(5)Pr(G_1) + P(5')Pr(G_2)]$

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Transformation Method (Cont'd)

- **Factoring Theorem:** For any network reliability measure R , probabilistic undirected graph G , and edge e of G , we have:

$$R(G) = p_e R(G \bullet e) + (1 - p_e) R(G - e)$$

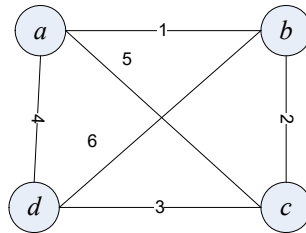
- $G \bullet e$ (G contract e): given $e = \{v_1, v_2\}$, $G \bullet e$ can be obtained by first removing e and then collapsing v_1 and v_2 into a single node v ; every edge involving v_1 or v_2 is replaced by an edge involving v .
- $G - e$ (G delete e): remove the edge e from the graph

Transformation Method (Cont'd)

- Use series and parallel transformations first
- Resort to edge-factoring only when no more series or parallel transformations can be made!

Hands on Problem (3)

- Find the two-terminal reliability from a to b using transformation method, given that each edge has a failure probability $q=0.1$.

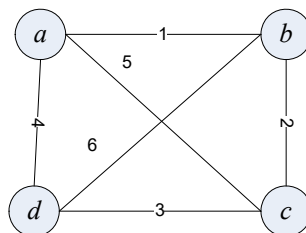


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Hands on Problem (4)

- Find the two-terminal reliability from a to c using transformation method, given that each edge has a failure probability $q=0.1$.



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Example Evaluation Methods (Agenda)

- ✓ State space enumeration method
- ✓ Cut-set and tie-set method
- ✓ Graph Transformation method
- **Binary decision diagrams based method**

Reference:

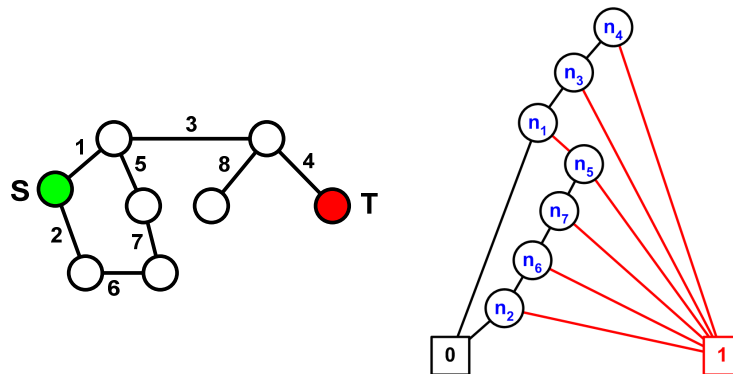
1. Xinyu Zang, Hairong Sun, Kishor S. Trivedi, "A BDD-Based Algorithm for Reliability Graph Analysis", <http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.44.6169>

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Binary Decision Diagrams Based Method

- Convert the graph into a BDD and then evaluate the BDD



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Algorithm for generating BDD from probabilistic graph

- Traverse the graph breadth-first to list all path-sets.
- Convert each pathset to an equivalent BDD by ANDing all the components in that path-set
- Generate total BDD by ORing all path-set BDDs

```

bdd_gen(start_node) {
  T_bdd = 0
  set start_node in this_path
  for (edge_i in the set of edges starting from start_node) {
    next_node = the other end of edge_i
    if (next_node == sink_node)
      subpath_bdd = edge_i_bdd
    else if (next_node is already in this_path)
      continue;
    else
      subpath_bdd = bdd_gen(next_node) AND edge_i_bdd
    T_bdd = T_bdd OR subpath_bdd
  }
  clear start_node in this_path
  return T_bdd
}
    
```

algorithm proposed by Zang et al.

All-Terminal and K-Terminal Reliability

- State space enumeration method
- Cut-set and tie-set method
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Reference:

1. Martin L. Shooman, "Reliability of Computer Systems and Networks: Fault Tolerance, Analysis, and Design", John & Sons Wiley, 2002, ISBN 0-471-29342-3 (Chapter 6.6).
2. Sy-Yen Kuo, Fu-Min Yeh, and Hung-Yau Lin, "Efficient and Exact Reliability Evaluation for Networks With Imperfect Vertices", IEEE Transactions on Reliability, Vol. 56, No. 2, June 2007.
<http://ieeexplore.ieee.org/iel5/24/4220773/04220790.pdf>
3. Gary Hardy, Corinne Lucet, and Nikolaos Limnios, "K-Terminal Network Reliability Measures With Binary Decision Diagrams", IEEE Transactions on Reliability, Vol. 56, No. 3, September 2007.
<http://ieeexplore.ieee.org/iel5/24/4298224/04298237.pdf?arnumber=4298237>

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